Basic vector analysis

Cartesian

 $\vec{r} = r "vector"$ $\hat{r} = r "unit vector" or the direction of \vec{r}$ $r = magnitude of \vec{r}$ $\vec{r} = (X\hat{\imath} + Y\hat{\jmath} + Z\hat{k})$ $\vec{r'} = (X'\hat{\imath} + Y'\hat{\jmath} + Z'\hat{k})$ $\vec{\mathcal{R}} = ((X - X')\hat{\imath} + (Y - Y')\hat{\jmath} + (Z - Z')\hat{k})$

Cylindrical

$$\vec{r} = (s, \varphi, z)$$

$$s = \sqrt{x^2 + y^2}$$

$$\varphi = tan^{-1}(\frac{y}{x})$$

$$z = z$$

Sphrerical

$$\vec{r} = (r, \Theta, \varphi)$$

$$r = \sqrt{x^2 + y^2 + z^2}$$

$$\Theta = tan^{-1}\sqrt{x^2 + y^2}/z$$

$$\varphi = tan^{-1}(\frac{y}{x})$$

Always Start with your r and r' definitions in Cartesian because cylindrical and spherical coordinates do not add and subtract easily.

Use cylindrical coordinates in cases where there is a line, ring, disk, or cylinder of charge

Use spherical in cases where there is a point charge, shell of charge, or sphere of charge.

Symmetry

In many problems certain axis and parameters can be eliminated via symmetric arguments

Symmetry involves a rotation, translation, or reflection about an axis resulting in the shape looking identical.

Symmetry can also result in components cancelling which can make a problem easier to deal with

Basic Electric field symmetries assuming constant charge density:

Sphere: variable in r Infinite line: variable in s Finite Cylinder: dependant on s and z Infinite plane: constant Ex: Find the direction of

Brute Force \vec{E} Field Equation

 $\vec{r} = r\hat{r} \qquad \vec{E} = \frac{1}{4\pi\varepsilon_0} \int \rho \frac{\vec{\mathcal{R}}}{\mathcal{R}^3} d\mathbf{\tau}' \\ \vec{E} = \frac{1}{4\pi\varepsilon_0} \int \rho \frac{\hat{\mathcal{R}}}{\mathcal{R}^2} d\mathbf{\tau}' \qquad \text{3D shape} \\ \vec{E} = \frac{1}{4\pi\varepsilon_0} \int \sigma \frac{\hat{\mathcal{R}}}{\mathcal{R}^2} da' \qquad \text{2D shape} \\ \vec{E} = \frac{1}{4\pi\varepsilon_0} \int \chi \frac{\hat{\mathcal{R}}}{\mathcal{R}^2} dl' \qquad \text{1D shape} \end{cases}$

Gauss's Law $\oint E(r) \cdot dA = \frac{1}{\varepsilon_0} \int \rho \, d\tau$ **Integral form**

Standard E Field Solutions

Point Charge

Infinite Plane

Cylinder/Line

$$\vec{E} = \frac{1}{4\pi\varepsilon_0} \frac{q}{r^2} \hat{r}$$
$$\vec{E} = \frac{\sigma}{2\varepsilon_0} \hat{n}$$
$$\vec{E} = \frac{\lambda}{2\pi\varepsilon_0 s} \hat{s}$$

Spherical surface (Ex):

$$\vec{E} = \frac{\alpha(a^4 - b^4)}{4\varepsilon_0 r^2} \hat{r}$$



Electric Potentials

 $E = -\nabla V$

$$V(b) = -\int_{a}^{b} \vec{E} \cdot \vec{dl} + V(a)$$

$$\nabla^2 V = -\frac{\rho}{\varepsilon_0}$$

$$V(r) = \frac{1}{4\pi\varepsilon_0} \int \frac{\rho(r)}{\mathcal{R}} d^3$$

Conductors

In a conductor E field is 0.

Outside a conductor the E field mimics a point charge and is perpendicular to the surface.

Net charge density is 0.

Any charge density is confined to the surface.



Work and Energy

$$W = \frac{1}{2} \sum_{i=1}^{n} q_i V(r_i)$$
$$W = \frac{1}{2} \int \rho(r) V(r) d^3 r$$
$$U_E = \frac{\epsilon_0}{2} \int |E|^2 d^3 r$$
$$W = U_2 - U_1$$

Capacitors

$$Q = CV$$

$$Q = V \times \frac{A\epsilon_0}{d}$$

$$U = \frac{\epsilon_0}{2} \left(\frac{Q^2}{A^2 \epsilon_0^2}\right) (Ad) = \frac{1}{2} \frac{Q^2 d}{A\epsilon_0} = \frac{1}{2} \frac{Q^2}{C} = \frac{1}{2} CV^2$$
Q+
A
Q+
A
Q-

Magnetostatics

$$F_{\text{Mag}} = q(\boldsymbol{v} \times \boldsymbol{B}) \quad (\text{Point charge})$$

$$F_{\text{Mag}} = \int (\boldsymbol{v} \times \boldsymbol{B}) \lambda \, dl = \int (\boldsymbol{I} \times \boldsymbol{B}) \, dl$$

$$F_{\text{Mag}} = \int (\boldsymbol{v} \times \boldsymbol{B}) \sigma \, da = \int (\boldsymbol{K} \times \boldsymbol{B}) \, da$$

$$F_{\text{Mag}} = \int (\boldsymbol{v} \times \boldsymbol{B}) \rho \, d\tau = \int (\boldsymbol{J} \times \boldsymbol{B}) \, d\tau$$





Steady Currents and Biot-Savart Law $\nabla J = -\frac{\partial \rho}{\partial t}$ Continuity equation $\nabla J = 0$ For steady currents $\boldsymbol{B}(\boldsymbol{r}) = \frac{\mu_0}{4\pi} \int \frac{\boldsymbol{I} \, \boldsymbol{x} \, \widehat{\boldsymbol{\mathcal{R}}}}{\mathcal{R}^2} \, \mathrm{d}\boldsymbol{l}' = \frac{\mu_0}{4\pi} I \int \frac{d\boldsymbol{l}' \boldsymbol{x} \, \widehat{\boldsymbol{\mathcal{R}}}}{\mathcal{R}^2}$ R dľ Example Find the magnetic field a distance s from a long straight wire carrying a steady current I $l' = s \tan \theta \rightarrow dl' = \frac{s}{\cos^2 \theta} d\theta$ S $\left| d\boldsymbol{l}' x \, \widehat{\boldsymbol{\mathcal{R}}} \right| = \mathrm{d}l' \, \mathrm{Sin}\alpha = \mathrm{d}l' \, \mathrm{Cos}\theta$ $s = \mathcal{R} \cos\theta \rightarrow \frac{1}{\mathcal{R}^2} = \frac{\cos^2\theta}{s^2}$ $B = \frac{\mu_0 I}{4\pi} \int_{\theta_1}^{\theta_2} \left(\frac{\cos^2\theta}{s^2}\right) \left(\frac{s}{\cos^2\theta}\right) \cos\theta \, d\theta = \frac{\mu_0 I}{4\pi} \int_{\theta_1}^{\theta_2} \cos\theta \, d\theta = \frac{\left\lfloor \frac{\mu_0 I}{4\pi s} (\sin\theta_2 - \sin\theta_1) \right\rfloor}{4\pi s}$ $B_{\text{infinite}_{\text{wire}}} = \frac{\mu_0 I}{2\pi\epsilon}$

Ampere's Law

$$\nabla x B = \mu_0 J \qquad \int (\nabla x B) \, \mathrm{d}a = \oint B \, \mathrm{d}l = \mu_0 \int J \, \mathrm{d}a$$
$$\int J \, \mathrm{d}a = \text{total current passing through the surface}$$
$$\boxed{\oint B \, \mathrm{d}l = \mu_0 I_{\mathrm{enc}}}$$

Example

Find the magnetic field a distance s from a long straight wire carrying a steady current I

$$\oint B. dl = B \int dl = B2\pi s = \mu_0 I_{enc} = \mu_0 I = > B = \frac{\mu_0 I}{2\pi s}$$

B-Field for different shapes

Magnetic field of an infinite uniform surface current $\mathbf{K} = k\hat{x}$ Sheet of current \mathbf{K} \mathbf{K} \mathbf{K}



Boundary Conditions



$$B^{\text{perp}}_{above} = B^{\text{perp}}_{below}$$



$$B^{||}_{above} - B^{||}_{below} = \mu_0 K$$

Other stuff to know

 $\nabla . B = 0 \qquad W_{\rm mag} = 0$

m = Ia (Magnetic dipole moment) Here a is the vector area of the loop

Maxwell's Equations

Equation	Name
$\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}$	Gauss' Law
$ abla imes ec B = -rac{dec B}{dt}$	Faraday's Law
$\nabla \cdot \vec{B} = 0$	No-Name Law/ Gauss' Law for B-fields
$\nabla \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{d\vec{E}}{dt}$	Ampere's Law

 $oldsymbol{
ho}$ — volume charge density (C/m³) J -- current density (A/m²)

Faraday's Law

$$\nabla \times \vec{E} = -\frac{d\vec{B}}{dt}$$

According to Stokes' Theorm

$$\int (\nabla \times \vec{E}) \cdot ds = \int \vec{E} \cdot dl = \frac{-d\phi_B}{dt}$$
$$\phi_B = \oint B \cdot dS$$

$$\varepsilon = -\frac{d\phi_B}{dt}$$
 Lenz's Law (emf.)

**Induced currents always oppose changes in magnetic field

Inductors: Loop of Wire

A loop of current produces current in any nearby loops.

$$\phi_{\rm B} = LI$$

For a magnetic field *produced by wires themselves*

$$\xi = -L\frac{\mathrm{d}I}{\mathrm{d}t}$$



Inductors: Solenoid

$$L=\frac{\mu_0 N^2 A}{l}$$

N- number of turns*A*- cross-sectional area*I*- length



Electric Dipoles

Dipole moment

$$\vec{p} = qr_1 - qr_2 = qd$$

Dipole moment- collection of charges

$$\vec{p} = \sum_{i} q_i d_i$$

Electric potential from dipole moment

$$\mathbf{V}(\vec{\mathbf{r}}) = \frac{1}{4\pi\varepsilon_0} \frac{\vec{\mathbf{p}}\cdot\hat{\mathbf{r}}}{\mathbf{r}^2}$$



**Note V
$$\rightarrow$$
1/r² and E \rightarrow 1/r³

Magnetic Dipoles

Remember:

--no magnetic monopoles

--cannot be decomposed like E dipoles



 $\overrightarrow{m} = IA$



m- magnetic dipole moment (Am²)A- vector normal to surface (area)

Matter Effects - Dielectrics

Materials that can be polarized in an applied field and thus slightly cancel the electric field. Parameterized by making the substitution:

 $\varepsilon_0 \to \varepsilon = \kappa \varepsilon_0$

 $\boldsymbol{\mathcal{K}}$ is the dielectric constant



Most common: insulator placed between two plates, capacitance becomes

$$C = \frac{\varepsilon A}{d} = \kappa \frac{\varepsilon_0 A}{d}$$



Electromagnetic waves - Wave Equation Assuming vacuum $\nabla \mathbf{x} (\nabla \mathbf{x} \mathbf{E}) = \nabla (\nabla \cdot \mathbf{E}) - \nabla^2 \mathbf{E} = -\frac{\partial}{\partial t} (\nabla \mathbf{x} \mathbf{B})$ $\nabla^2 \mathbf{E} = \mu_0 \varepsilon_0 \frac{\partial^2 \mathbf{E}}{\partial t^2}$ $\nabla^2 \mathbf{B} = \mu_0 \varepsilon_0 \frac{\partial^2 \mathbf{B}}{\partial t^2}$ Similarly And

Electromagnetic waves - Wave Equation

Wave solutions have the explicit form

$$\widetilde{\mathbf{E}}(\mathbf{r}) = \widetilde{E}_0 e^{i(\mathbf{k}\cdot\mathbf{r}-\omega t)} \widehat{\mathbf{n}} \quad \widetilde{\mathbf{B}}(\mathbf{r}) = \frac{1}{c} \widetilde{E}_0 e^{i(\mathbf{k}\cdot\mathbf{r}-\omega t)} (\widehat{\mathbf{k}} \ge \widehat{\mathbf{n}})$$

Where k is the propagation vector describing the direction in which the wave travels and \hat{n} is the polarization vector of the electric field only. Rule for notation: calculate everything in the complex formalism and then take the real part $\mathbf{E} = \operatorname{Re}(\tilde{\mathbf{E}})$

Fine for superpositions, since the real part of a sum is the sum of the real parts, but it's more complicated for products.

Electromagnetic waves - Poynting Vector

Flux of energy of the wave

$$\mathbf{S} = \frac{1}{\mu_0} (\mathbf{E} \ge \mathbf{B}) = \frac{1}{2\mu_0} \operatorname{Re}(\tilde{\mathbf{E}} \ge \tilde{\mathbf{B}}^*)$$

Intensity of the wave is often easier to deal with because of extremely high frequencies

$$I = \langle S \rangle = \frac{1}{2} c \varepsilon_0 E_0^2$$

Electromagnetic waves - Radiation

Larmor formula: An accelerating point charge radiates total power

$$P = \frac{q^2 a^2}{6\pi\varepsilon_0 c^3} = \frac{\mu_0 q^2 a^2}{6\pi c}$$

Only holds for small velocities. Oscillating dipole with dipole moment

$$\mathbf{p}(t) = p_0 \cos{(\omega t)} \hat{\mathbf{z}}$$

And intensity

$$\langle S \rangle = \left(\frac{\mu_0 p_0^2 \omega^4}{32\pi^2 c}\right) \frac{\sin^2 \theta}{r^2}$$

Falls off like $\frac{1}{r^2}$ and the $sin^2\theta$ means no radiation occurs along the dipole axis

Electromagnetic waves - Radiation

Integrate over a sphere of radius r gives the total power

$$\langle P \rangle = \frac{\mu_0 p_0^2 \omega^4}{12\pi c}$$

Analogous formula for the magnetic dipole radiation

$$\langle P \rangle = \frac{\mu_0 m_0^2 \omega^4}{12\pi c^3}$$

Where m_0 is the average magnetic dipole moment.