

Problem 1

$$x^4 + 62x^2 + 288x + 1825 \text{ solve } \rightarrow \begin{pmatrix} -3 + 4i \\ -3 - 4i \\ 3 + 8i \\ 3 - 8i \end{pmatrix}$$

The answer asked for was the second of these:

-3 - 4*i

Problem 2

$\mu := 7000 \quad \sigma := 500$

$\text{pnorm}(7500, \mu, \sigma) - \text{pnorm}(7500, \mu, \sigma) = 0$

zero

Problem 3

$\text{pnorm}(7600, \mu, \sigma) - \text{pnorm}(6600, \mu, \sigma) = 0.673$

0.673

Problem 4 We are given four equations in sentence form. Let's convert them into math notation:

$A = \frac{A + B + C + D}{4}$

In other words,

$3 \cdot A - 1B - 1C - 1D = 0$

$B = \frac{A + C + D}{3} - 12$

$-1A + 3 \cdot B - 1C - 1D = -36$

$C = \frac{B + D}{2} + 9$

$0 \cdot A - 1B + 2 \cdot C - 1D = 18$

$D = 10 \cdot (A - B) - 4$

$10 \cdot A - 10 \cdot B + 0 \cdot C - 1D = 4$

In Matrix notation, this becomes:

$$M := \begin{pmatrix} 3 & -1 & -1 & -1 \\ -1 & 3 & -1 & -1 \\ 0 & -1 & 2 & -1 \\ 10 & -10 & 0 & -1 \end{pmatrix} \quad \underline{\underline{K}} := \begin{pmatrix} 0 \\ -36 \\ 18 \\ 4 \end{pmatrix}$$

Therefore, the exam scores are:

$\text{Grades} := M^{-1} \cdot K$

$$\text{Grades} = \begin{pmatrix} 83 \\ 74 \\ 89 \\ 86 \end{pmatrix}$$

So, it looks like Bobby got a 74 on this test.

Also, the highest grade was Cassie (89) on this test.

Problem 5

Problem 6

$$\chi(k) := k \cdot \begin{pmatrix} -7 \\ 9i \end{pmatrix} \quad \chi_{\text{star}}(k) := k \cdot \begin{pmatrix} -7 \\ -9i \end{pmatrix}$$

$$\chi_{\text{star}}(k)^T \cdot \chi(k) - 1 \text{ solve } \rightarrow \begin{pmatrix} \sqrt{130} \\ 130 \\ -\sqrt{130} \\ 130 \end{pmatrix}$$

We probably want the positive answer....

$$k := \frac{\sqrt{130}}{130}$$

k = 0.0877

Problem 7

$$\begin{matrix} \text{time} := \\ \text{pos} := \end{matrix} \begin{pmatrix} 3 \\ 6 \\ 9 \\ 12 \\ 15 \end{pmatrix} \begin{pmatrix} 50 \\ 63 \\ 63 \\ 41 \\ 6 \end{pmatrix} \quad M := \begin{bmatrix} \sum_{i=0}^4 (\text{time}_i)^0 & \sum_{i=0}^4 (\text{time}_i)^1 & \sum_{i=0}^4 (\text{time}_i)^2 \\ \sum_{i=0}^4 (\text{time}_i)^1 & \sum_{i=0}^4 (\text{time}_i)^2 & \sum_{i=0}^4 (\text{time}_i)^3 \\ \sum_{i=0}^4 (\text{time}_i)^2 & \sum_{i=0}^4 (\text{time}_i)^3 & \sum_{i=0}^4 (\text{time}_i)^4 \end{bmatrix} \quad k := \begin{bmatrix} \sum_{i=0}^4 [(\text{time}_i)^0 \cdot \text{pos}_i] \\ \sum_{i=0}^4 [(\text{time}_i)^1 \cdot \text{pos}_i] \\ \sum_{i=0}^4 [(\text{time}_i)^2 \cdot \text{pos}_i] \end{bmatrix}$$

$$M = \begin{pmatrix} 5 & 45 & 495 \\ 45 & 495 & 6075 \\ 495 & 6075 & 79299 \end{pmatrix} \quad k = \begin{pmatrix} 223 \\ 1677 \\ 15075 \end{pmatrix}$$

Note that I had to ask MathCAD to show me the answers as decimals instead of in scientific notation.

So it seems that $M_{\text{row3, coll}}$ is 495.

And it seems that k_{row2} is 1677.

Problem 8

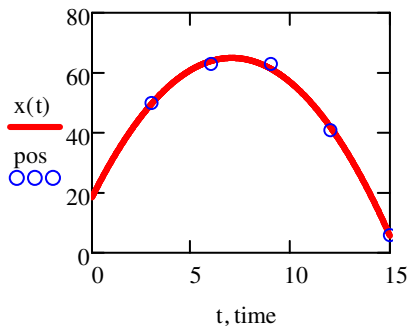
Problem 9

The fit coefficients are: $a := M^{-1} \cdot k$ In other words: $x(t) := a_0 + a_1 \cdot t + a_2 \cdot t^2$

$x(14) = 19.711$

Problem 10

We could plot this to see if this result is reasonable:



Since $x(t) = x_0 + v_0 \cdot t + \frac{1}{2} \cdot a \cdot t^2$, the acceleration must be:

$$\frac{1}{2} \cdot a = a_2, \text{ or } a = 2 a_2. \text{ In other words:}$$

$$a := 2 \cdot a_2$$

$$a = -1.873 \frac{\text{m}}{\text{s}^2}$$

Problem 11

$$\begin{pmatrix} 2 & 3 & -1 \\ 1 & 2 & 0 \\ 4 & 3 & A1 \end{pmatrix} \text{ solve } \rightarrow -5$$

Apparently, if A is -5 this problem can't be solved.

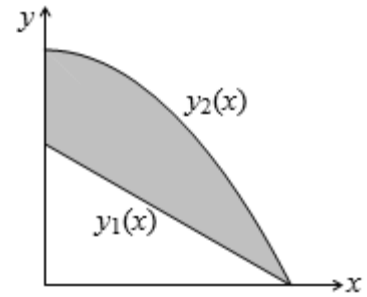
Problem 12

$$y_2(x) := 36 - 4 \cdot x^2$$

On the x-axis, when $y = 0$, $x_{\max} := \sqrt{\frac{-36}{-4}}$

For the straight line, slope = rise/run: $m := \frac{-18}{x_{\max}}$

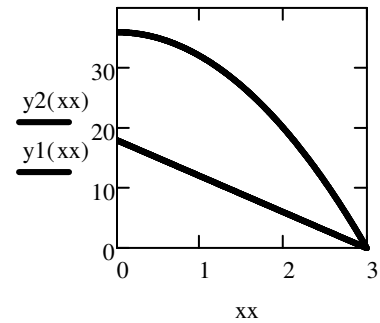
So, for the straight line: $y_1(x) := m \cdot x + 18$



$$A := \int_0^{x_{\max}} y_2(x) - y_1(x) dx \quad \boxed{A = 45}$$

Problem 13

$$y_{cm} := \frac{\int_0^{x_{\max}} (y_2(x) - y_1(x)) \cdot \left(\frac{y_1(x) + y_2(x)}{2}\right) dx}{A} \quad \boxed{y_{cm} = 19.44}$$



Problem 14

$$M := \begin{pmatrix} 0.62932 & 0 & 0.77715 \\ 0 & 1 & 0 \\ -0.77715 & 0 & 0.62932 \end{pmatrix}$$

Note that $|M| = 1$, so this really is a rotation matrix.

Clearly, the middle column is 010, so this matrix rotates about the y-axis. y

There are several ways to find the angle of rotation. We can recall that:

Problem 15

$$M_{\text{rot}} := \begin{pmatrix} \cos(\theta) & 0 & -\sin(\theta) \\ 0 & 1 & 0 \\ \sin(\theta) & 0 & \cos(\theta) \end{pmatrix}$$

However, the problem with solving for θ is that there is more than one angle θ such that $\cos(\theta) = 0.62932$. Let's find them:

$$\cos(\theta) = 0.62932 \text{ solve } \rightarrow \begin{pmatrix} -0.89011842170412464998 \\ 0.89011842170412464998 \end{pmatrix}$$

Suppose that the correct angle is $+0.89011$ radians. Then we better hope that $+\sin(\theta) = -0.77715$.

$$\sin(0.89011) = 0.777$$

Hmmm... that isn't right. Let's try the other angle:

$$\sin(-0.89011) = -0.777$$

That looks better. Let's convert it to degrees:

$$-0.890118 \cdot \frac{180}{\pi} = -51$$

So, the answer is -51 degrees. However, we were asked to choose an angle between 0 and 358 degrees.

$$\theta := -51 + 360$$

The answer is therefore 309 deg

An alternative method of solution would be to just have M act on a known vector, such as (1,0,0):

$$M \cdot \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0.62932 \\ 0.00000 \\ -0.77715 \end{pmatrix} \quad \theta := \text{atan}\left(\frac{-0.77715}{0.62932}\right)$$

Problem 16

$$M := \begin{pmatrix} 6 & 5 \\ 5 & -3 \end{pmatrix} \quad \text{eigenvals}(M) = \begin{pmatrix} -5.227 \\ 8.227 \end{pmatrix}$$

Problem 17

$$\text{eigenvecs}(M) = \begin{pmatrix} 0.407 & -0.914 \\ -0.914 & -0.407 \end{pmatrix}$$

Unfortunately, these aren't formatted the same way that the question asked for. Specifically, the x-component of the 2nd eigenvector should be positive:

$$\text{Eigenvectors} := \begin{pmatrix} 0.407 & 0.914 \\ -0.914 & 0.407 \end{pmatrix}$$

In the order that the question asked for, this is:

$$\begin{matrix} \text{y-component 1:} & -0.914 \\ \text{x-component 2:} & +0.914 \\ \text{y-component 2:} & +0.407 \end{matrix}$$

Problem 18

$$\underline{m} := \begin{pmatrix} 5 \\ 7 \\ 5 \end{pmatrix} \quad \underline{x} := \begin{pmatrix} 0 \\ 2 \\ -3 \end{pmatrix} \quad y := \begin{pmatrix} 0 \\ -2 \\ -3 \end{pmatrix} \quad z := \begin{pmatrix} 0 \\ 3 \\ 4 \end{pmatrix}$$

$$I_{xy} := \sum_{i=0}^2 (-m_i \cdot x_i \cdot y_i)$$

Problem 19

$$I_{yy} := \sum_{i=0}^2 \left[m_i \cdot \left[(x_i)^2 + (z_i)^2 \right] \right]$$

Problem 20

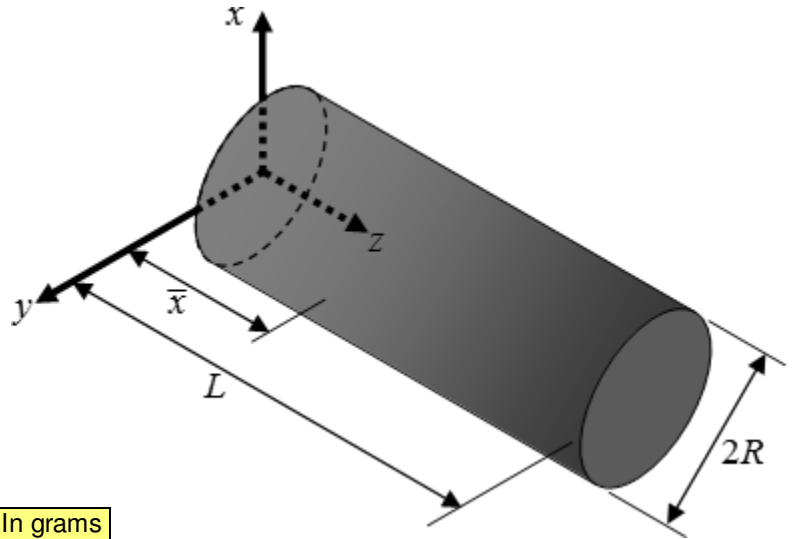
$$I_{zx} := \sum_{i=0}^2 (-m_i \cdot x_i \cdot z_i)$$

Problem 21

$$\underline{L} := 90 \quad \underline{R} := 27$$

$$\rho(z) := 4 + 23 \cdot \frac{z}{L}$$

Check : $\rho(0) = 4 \quad \rho(L) = 27$



$$m := \int_0^L \rho(z) \cdot \pi \cdot R^2 \, dz \quad m = 3.195 \times 10^6 \quad \text{In grams}$$

Problem 22

$$z_{cm} := \frac{\int_0^L z \cdot \rho(z) \cdot \pi \cdot R^2 \, dz}{m} \quad z_{cm} = 56.129 \quad \text{In cm}$$

Problem 23

$$I_{xx} := \int_0^L \int_0^R \int_0^{2\pi} \rho(z) \cdot r \cdot \left[(r \cdot \sin(\theta))^2 + z^2 \right] \, d\theta \, dr \, dz \quad I_{xx} = 1.241 \times 10^{10} \quad \text{In g*cm}^2$$