

The calculation is similar for the second parametrization:

$$x = \cos(t^2); \quad dx = -2t \sin(t^2) dt; \quad y = \sin(t^2); \quad dy = 2t \cos(t^2) dt.$$

Check the last (easy) step.

This gives  $\leftarrow$

$$\int_{\gamma} -y dx + x dy = \int_0^{\sqrt{\pi}} (\sin^2(t^2) + \cos^2(t^2)) 2t dt = \pi.$$

The results are the same, as they should be. ■

**The general case** A general argument for independence of parametrization in line integrals resembles the specific calculation in Example 3. Suppose we are given any two differentiable parametrizations

$$\mathbf{X}_1(s) = (x_1(s), y_1(s)) \quad \text{and} \quad \mathbf{X}_2(t) = (x_2(t), y_2(t))$$

for the curve  $\gamma$ , where  $a \leq s \leq b$  and  $c \leq t \leq d$ . For the line integral  $\int_{\gamma} P dx + Q dy$ , these parametrizations lead, respectively, to two ugly integrals:

$$I_1: \int_a^b \left( P(\mathbf{X}_1(s)) \frac{dx_1}{ds} + Q(\mathbf{X}_1(s)) \frac{dy_1}{ds} \right) ds$$

$$I_2: \int_c^d \left( P(\mathbf{X}_2(t)) \frac{dx_2}{dt} + Q(\mathbf{X}_2(t)) \frac{dy_2}{dt} \right) dt.$$

These integrals look complicated, to be sure, and much notation is involved. But here we care only that  $I_1$  and  $I_2$  have the *same* value. To see this one shows first that  $s$  is a differentiable function of  $t$  such that  $\mathbf{X}_2(t) = \mathbf{X}_1 \circ s$ . In other words,

$$\mathbf{X}_2(t) = (x_2(t), y_2(t)) = \mathbf{X}_1(s(t)) = (x_1(s(t)), y_1(s(t))).$$

(Showing in general that  $s(t)$  is differentiable is slightly delicate. In Example 3, we had simply  $s = t^2$ , which is clearly differentiable.) In particular,  $s(c) = a$  and  $s(d) = b$ .

Assuming the foregoing facts, we can make the change of variable  $s = s(t)$  in  $I_1$ , which (despite its complicated appearance) is an ordinary integral of the single-variable type. The happy result is that  $I_2$  emerges:

$$\begin{aligned} I_1 &= \int_a^b \left( P(\mathbf{X}_1(s)) \frac{dx_1}{ds} + Q(\mathbf{X}_1(s)) \frac{dy_1}{ds} \right) ds \\ &= \int_c^d \left( P(\mathbf{X}_1(s(t))) \frac{dx_1}{ds} + Q(\mathbf{X}_1(s(t))) \frac{dy_1}{ds} \right) \frac{ds}{dt} dt \\ &= \int_c^d \left( P(\mathbf{X}_2(t)) \frac{dx_2}{dt} + Q(\mathbf{X}_2(t)) \frac{dy_2}{dt} \right) dt = I_2. \end{aligned}$$

(We used the ordinary chain rule in the last line, in the form

$$\frac{dx_1}{ds} \cdot \frac{ds}{dt} = \frac{d}{dt} (x_1(s(t))) = \frac{dx_2(t)}{dt}$$

for the first summand and similarly in  $y$  for the second.) We conclude that  $I_1 = I_2$ , just as desired.

## The fundamental theorem for line integrals

One version of the fundamental theorem of elementary calculus relates the integral and the derivative: If a function  $f$  and its derivative  $f'$  are continuous on  $[a, b]$ , then

$$\int_a^b f'(x) dx = f(b) - f(a).$$

(There are other ways to state the fundamental theorem of calculus; this version is best for present purposes.)

A similar “fundamental theorem” holds for line integrals. To ensure that all the ingredients exist, we assume that the function  $h(x, y)$  has continuous partial derivatives on and near the curve  $\gamma$ , and that  $\gamma$  is smooth, except perhaps at its endpoints.

**THEOREM 2 (Fundamental theorem for line integrals)** Let  $h(x, y) : \mathbb{R}^2 \rightarrow \mathbb{R}$  be a function. Let  $\gamma$  be a smooth, oriented curve starting at  $\mathbf{X}_0 = (x_0, y_0)$  and ending at  $\mathbf{X}_1 = (x_1, y_1)$ . Then

$$\int_{\gamma} \nabla h \cdot d\mathbf{X} = h(\mathbf{X}_1) - h(\mathbf{X}_0).$$

If  $\gamma$  is a closed curve (i.e.,  $\mathbf{X}_1 = \mathbf{X}_0$ ), then

$$\int_{\gamma} \nabla h \cdot d\mathbf{X} = 0.$$

**Proof** The proof is a pleasing and straightforward exercise with the chain rule. Let the curve  $\gamma$  be parametrized, as usual, by a function

$$\mathbf{X}(t) = (x(t), y(t)); \quad a \leq t \leq b.$$

(Because  $\gamma$  is smooth, we can assume that  $x'$  and  $y'$  are continuous functions, and thus all the needed integrals exist.) Then the line integral has the form

$$I = \int_{\gamma} \nabla h \cdot d\mathbf{X} = \int_a^b \left( h_x(\mathbf{X}(t)), h_y(\mathbf{X}(t)) \right) \cdot \mathbf{X}'(t) dt.$$

Now the composite  $h(\mathbf{X}(t))$  is a new function of  $t$ , and, by the chain rule in several variables,

$$\frac{d}{dt} (h(\mathbf{X}(t))) = \nabla h(\mathbf{X}(t)) \cdot \mathbf{X}'(t).$$

In other words, the integrand in the last integral above is the  $t$ -derivative of  $h(\mathbf{X}(t))$ . Therefore, by the ordinary fundamental theorem of calculus,

$$I = \int_a^b \frac{d}{dt} (h(\mathbf{X}(t))) dt = h(\mathbf{X}(b)) - h(\mathbf{X}(a)) = h(x_1, y_1) - h(x_0, y_0),$$

as claimed. ■