

Problem set 5 exemplars and comments.

You might have missed it, but somewhere along the way this course became geometric and visual. You cannot ignore that aspect. Calc III was heavily geometric and there are ways that our course is moreso. It is important to be able to reason both visually and also with equations. The first two problems on this problem set require visual reasoning. You need to not be averse to drawing pictures.

10.3.7 is about how paths fit together. Remember that  $\omega$  is not defined at the origin in this problem. You need to find a region not containing the origin that is contractible where it is defined. That is the basic idea - cutting the region into pieces that work nicely.

10.3.8 is for any two points. It is important to start with the two points and then two paths connecting them, and finally that makes a curve to which the given can be applied.

10.3.14 is rather straightforward - differentiate  $\omega$  and set the result equal to zero. Each term must be zero, so gather them together to get three equations. Reasons matter.

10.3.19 show closed by differentiating and then integrate by different variables. Do NOT add the results. Smoosh them together, or see how they are combined on pp. 292-293.

10.5.5 is rather straightforward - please get in the habit of using the FTC by differentiating, not by remembering ugly formulae. Remember changing order of integration is allowed as always in Calc III, it is not a sign change by changing orientation.

10.5.9 translate first (as the directions say) so that there are no more triangles in your work. Then look at each side and see that they are related by the FTC (i.e. take the derivative of the 1-form and see that it equals the 2-form). Be careful always each step on the way to match the dimensions of your integration location to the order of the form.

10.5.14 the torus here is produced by rotating the circle  $(x-4)^2 + z^2 = 1$  around the  $y$ -axis. The derivative of the 2-form is  $3dx dy dz$ , so this is, in the end, merely finding 3 times the volume of this particular torus. There is a parametrisation (including bounds) in the back. It is your job to find the Jacobian, either from a determinant of a matrix or by multiplying  $dx dy$  and  $dz$  in exterior algebra. The  $\rho$ - $\theta$ - $\phi$  orientation works fine here. In this case because you are finding 3 times the volume, if you get a negative final answer, you know it is incorrect.

On both of these last problems (and always) you are required to follow directions. If it doesn't say how to do a problem, you are free to choose your own way. If it says "Use Gauß's theorem" and you don't, you have not done the problem.

Remember you have a quiz on this material coming soon (open 30 April - 1 May).

10.3

7) let  $\omega$  be closed 1-form in  $\mathbb{R}^2$  w/ one singularity @  $(0,0)$ 

Show that if  $C_1$  &  $C_2$  are any pair of closed curves encircling (same direction) the origin, then

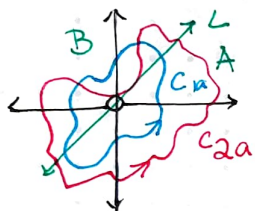
$$\oint_{C_1} \omega = \oint_{C_2} \omega$$

o note pg 2938 "if no arrow is given, it is assumed that the [loop] curve is following the counter clockwise direction"

o Poincaré's Lemma: if  $\omega$  is closed, on a contractible region, then  $\omega$  is exact in that region

consider the line  $L$  crossing through  $(0,0)$ , dividing  $\mathbb{R}^2$  into two contractible subsets  $A$  and  $B$  (one of the sets contain  $L$ ). Then  $\omega$  is exact over  $A$  and exact over  $B$ .

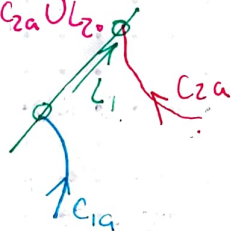
let  $C_{1a}$  &  $C_{2a}$  be the segments of loops  $C_1, C_2$  in  $A$ , and let  $C_{1b}, C_{2b}$  be the segments of  $C_1, C_2$  in  $B$ , and  $L_1, L_2$  be the segments connecting  $C_{1a}$  and  $C_{2a}$ , etc.



now, consider the closed loops  $C_{1a} \cup L_1 \cup C_{2a} \cup L_2$

Because  $\omega$  is exact and  $C_{1a} \cup L_1 \cup C_{2a} \cup L_2$  is closed,

$$\int_{C_{1a} \cup L_1 \cup C_{2a} \cup L_2} \omega = \int_{\emptyset} d\omega = 0$$



On the other side, we have an opposite-oriented loop ( $C_{1a}$  is oriented ccwise)

$$\int_{C_{1b} \cup L_2 \cup C_{2b} \cup L_1} \omega = \int_{\emptyset} d\omega = 0$$

composing our 4 loops cancels the contribution along  $L_1$  and  $L_2$

$$\int_{C_{1a}} \omega + \int_{L_1} \omega + \int_{-C_{2a}} \omega + \int_{L_2} \omega + \int_{C_{1b}} \omega + \int_{-L_2} \omega + \int_{-C_{2b}} \omega + \int_{-L_1} \omega = 0$$

Grouping like terms:

$$(\int_{C_{1a}} \omega + \int_{C_{1b}} \omega) + (\int_{-C_{2a}} \omega + \int_{-C_{2b}} \omega) + (\int_{L_1} \omega + \int_{-L_1} \omega) + (\int_{L_2} \omega + \int_{-L_2} \omega) = 0$$

$$\oint_{C_1} \omega + \int_{-C_2} \omega + 0 + 0 = 0$$

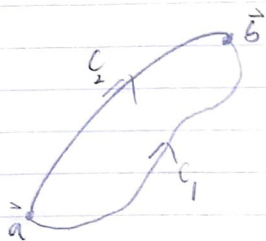
$$\oint_{C_1} \omega - \oint_{C_2} \omega = 0 \quad \square$$

§ Show that if  $W$  is a differential 1-form in  $\mathbb{R}^2$  for which the integral around any closed curve is 0 then the integral of  $W$  between any two points is independent of the path.

We know any integral  $W$  over a closed curve

$$\oint_C W = 0$$

now assume we have two points  $a$  and  $b$  that are on a closed path  $C$



let  $C_1$  and  $C_2$  be two paths inside  $R$  that both start at  $a$  and end at  $b$

let  $C$  be the curve obtained by taking the  $C_1$  path from  $a$  to  $b$  and the path from  $b$  to  $a$  along  $C_2$  in the reverse direction

Since the curve  $C$  is closed that means

$$0 = \oint_C W = \int_{C_1} W + \int_{C_2} W$$

therefore the integral of  $W$  between any two points is independent of the path.

(14)

For a closed 1-form of the form

$\omega = f dx + g dy + h dz$ , find the partial differential equations that must hold for  $d\omega = 0$  to be true.



$$\begin{aligned}
 w &= f dx + g dy + h dz \\
 dw &= \left( \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz \right) dx \\
 &\quad + \left( \frac{\partial g}{\partial x} dx + \frac{\partial g}{\partial y} dy + \frac{\partial g}{\partial z} dz \right) dy \\
 &\quad + \left( \frac{\partial h}{\partial x} dx + \frac{\partial h}{\partial y} dy + \frac{\partial h}{\partial z} dz \right) dz = 0
 \end{aligned}$$

$$\begin{aligned}
 &= \frac{\partial f}{\partial y} dy dx + \frac{\partial f}{\partial z} dz dx + \frac{\partial g}{\partial x} dx dy + \frac{\partial g}{\partial z} dz dy \\
 &\quad + \frac{\partial h}{\partial x} dx dz + \frac{\partial h}{\partial y} dy dz \\
 &= \left( \frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) dx dy + \left( \frac{\partial f}{\partial z} - \frac{\partial h}{\partial x} \right) dz dx \\
 &\quad + \left( \frac{\partial h}{\partial y} - \frac{\partial g}{\partial z} \right) dy dz = 0
 \end{aligned}$$

$\therefore$  the following PDEs hold:

$$\frac{\partial g}{\partial x} = \frac{\partial f}{\partial y}, \quad \frac{\partial f}{\partial z} = \frac{\partial h}{\partial x}, \quad \frac{\partial h}{\partial y} = \frac{\partial g}{\partial z}$$

### Problem 10.3.19:

1. Let  $\omega = (2x + y)dx + (x + zt)dy + (yt - t)dz + (yz - z)dt$ . For a differential form to be closed, we must satisfy  $d\omega = 0$ .

Taking the differential of the 1-form,

$$\begin{aligned}d\omega &= d((2x + y)dx + (x + zt)dy + (yt - t)dz + (yz - z)dt) \\ &= (2dx + dy)dx + (dx + tdz + zdt)dy + (tdy + ydt - dt)dz + (zdy + ydz - dz)dt \\ &= dydx + dx dy + t dz dy + z dt dy + t dy dz + y dt dz - dt dz + z dy dt + y dz dt - dz dt \\ &= 0\end{aligned}$$

Therefore,  $\omega$  is closed and as a result, a scalar field  $F$  exists that satisfies  $\omega = dF$ .

Finding  $dF$  calls for integrating each individual "component" of the 1-form  $\omega$ :

$$\frac{\partial F}{\partial x} = 2x + y \longrightarrow \int \frac{\partial F}{\partial x} dx = \int 2x + y dx$$

$$\implies F(x, y, z, t) = x^2 + xy + f(y, z, t)$$

$$\frac{\partial F}{\partial y} = x + zt \longrightarrow \int \frac{\partial F}{\partial y} dy = \int x + zt dy$$

$$\implies F(x, y, z, t) = xy + yzt + g(x, z, t)$$

$$\frac{\partial F}{\partial z} = yt - t \longrightarrow \int \frac{\partial F}{\partial z} dz = \int yt - t dz$$

$$\implies F(x, y, z, t) = yzt - zt + h(x, y, t)$$

$$\frac{\partial F}{\partial t} = yz - z \longrightarrow \int \frac{\partial F}{\partial t} dt = \int yz - z dt$$

$$\implies F(x, y, z, t) = yzt - zt + j(x, y, z)$$

Thus by inspection, the scalar field should take the form

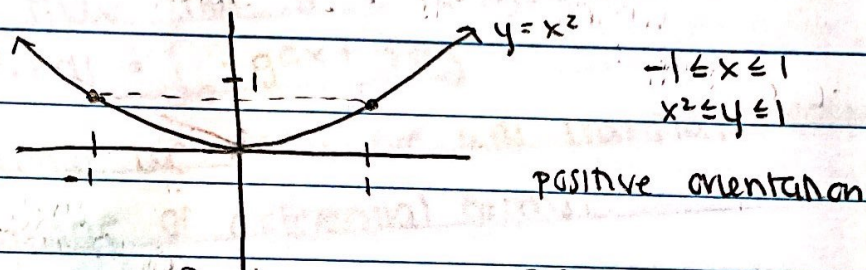
$$F(x, y, z, t) = x^2 + xy + yzt - zt$$



#5. Use Green's theorem to evaluate

$$\oint_C yx + x^2 dy$$

where  $C$  follows the parabola  $y = x^2$  from  $(-1, 1)$  to  $(1, 1)$  and then returns on the straight line from  $(1, 1)$  to  $(-1, 1)$



Green's Theorem is  $\int_C P dx + Q dy = \iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy$

$$\oint_C yx + x^2 dy = \int_{-1}^1 \int_{x^2}^1 (2x - 1) dy dx = \int_{-1}^1 [2xy - y]_{x^2}^1 dx$$

$$= \int_{-1}^1 [(2x - 1) - (2x^3 - x^2)] dx = \int_{-1}^1 2x - 1 - 2x^3 + x^2 dx$$

$$= \left[ \frac{2x^2}{2} - x - \frac{2x^4}{4} + \frac{x^3}{3} \right]_{-1}^1 = \left( 1 - 1 - \frac{1}{2} + \frac{1}{3} \right) - \left( 1 + 1 - \frac{1}{2} - \frac{1}{3} \right) = -\frac{4}{3}$$

$$9) a) \oint_{\partial R} \frac{\partial g}{\partial n} ds = \oint_{\partial R} \nabla g \cdot \vec{n} ds = \oint_{\partial R} \left( -\frac{\partial g}{\partial y} dx + \frac{\partial g}{\partial x} dy \right)$$

$$\int_R \nabla^2 g dx dy = \int_R \left( \frac{\partial^2 g}{\partial x^2} + \frac{\partial^2 g}{\partial y^2} \right) dx dy$$

By the fundamental theorem of calculus, we know that

$\oint_{\partial M} \omega = \int_M d\omega$  if we let  $\omega = -\frac{\partial g}{\partial y} dx + \frac{\partial g}{\partial x} dy$ , then

$$d\omega = d\left(-\frac{\partial g}{\partial y} dx + \frac{\partial g}{\partial x} dy\right) = d\left(-\frac{\partial g}{\partial y}\right) dx + d\left(\frac{\partial g}{\partial x}\right) dy = \left(dx - \frac{\partial^2 g}{\partial y^2} dy\right) dx + \left(\frac{\partial^2 g}{\partial x^2} dx + dy\right) dy = \left(-\frac{\partial^2 g}{\partial y^2} dx dy + \frac{\partial^2 g}{\partial x^2} dx dy\right) = \left(\frac{\partial^2 g}{\partial x^2} + \frac{\partial^2 g}{\partial y^2}\right) dx dy. \text{ Thus,}$$

$$\oint_{\partial R} \frac{\partial g}{\partial n} ds = \oint_{\partial R} \left(-\frac{\partial g}{\partial y} dx + \frac{\partial g}{\partial x} dy\right) = \int_R \left(\frac{\partial^2 g}{\partial x^2} + \frac{\partial^2 g}{\partial y^2}\right) dx dy = \int_R \nabla^2 g dx dy$$

$$b) \oint_{\partial R} f \frac{\partial g}{\partial n} ds = \oint_{\partial R} f \nabla g \cdot \vec{n} ds = \oint_{\partial R} \left(-f \frac{\partial g}{\partial y} dx + f \frac{\partial g}{\partial x} dy\right)$$

$$\int_R (f \nabla^2 g + \nabla f \cdot \nabla g) dx dy = \int_R \left(f \frac{\partial^2 g}{\partial x^2} + f \frac{\partial^2 g}{\partial y^2}\right) + \left(\frac{\partial f}{\partial x} \frac{\partial g}{\partial y} + \frac{\partial f}{\partial y} \frac{\partial g}{\partial x}\right) dx dy$$

$$\text{If we let } \omega = -f \frac{\partial g}{\partial y} dx + f \frac{\partial g}{\partial x} dy, \text{ then } d\omega = d\left(-f \frac{\partial g}{\partial y}\right) dx + d\left(f \frac{\partial g}{\partial x}\right) dy \\ = \left(-f \left(dx + \frac{\partial^2 g}{\partial y^2} dy\right) + \left(-\frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy\right) \frac{\partial g}{\partial y}\right) dx + \left(f \left(\frac{\partial^2 g}{\partial x^2} dx + dy\right) + \left(\frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy\right) \frac{\partial g}{\partial x}\right) dy \\ = \left(f \frac{\partial^2 g}{\partial y^2} + \frac{\partial f}{\partial y} \frac{\partial g}{\partial y} + f \frac{\partial^2 g}{\partial x^2} + \frac{\partial f}{\partial x} \frac{\partial g}{\partial x}\right) dx dy. \text{ Thus, by the}$$

fundamental theorem of calculus

$$\oint_{\partial R} f \frac{\partial g}{\partial n} ds = \oint_{\partial R} \left(-f \frac{\partial g}{\partial y} dx + f \frac{\partial g}{\partial x} dy\right) = \int_R \left(f \frac{\partial^2 g}{\partial x^2} + f \frac{\partial^2 g}{\partial y^2} + \frac{\partial f}{\partial x} \frac{\partial g}{\partial x} + \frac{\partial f}{\partial y} \frac{\partial g}{\partial y}\right) dx dy$$

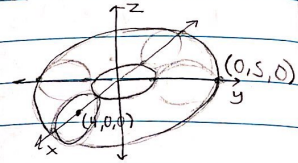
$$= \int_R (f \nabla^2 g + \nabla f \cdot \nabla g) dx dy, \text{ as desired}$$



use parametrization  $x = (4 + \rho \cos \phi) \cos \theta$   
 $0 \leq \rho \leq 1$   $0 \leq \theta \leq 2\pi$   $0 \leq \phi \leq 2\pi$   $z = \rho \sin \phi$   
 $y = (4 + \rho \cos \phi) \sin \theta$

14) Sketch the torus given by the equation  $(r-4)^2 + z^2 = 1$ , where  $x = r \cos \theta$  and  $y = r \sin \theta$ .  
 Use Gauss's Theorem to determine the rate @ which the flow described by  $x dy dz + y dz dx + z dx dy$  crosses the surface of this torus.

$$\begin{matrix} x \\ y \\ z \end{matrix} \begin{bmatrix} \rho & \theta & \phi \\ \cos \phi \cos \theta d\rho & -(4 + \rho \cos \phi) \sin \theta d\theta & -\rho \sin \phi \cos \theta d\phi \\ \cos \phi \sin \theta d\rho & (4 + \rho \cos \phi) \cos \theta d\theta & -\rho \sin \phi \sin \theta d\phi \\ \sin \phi d\rho & 0 d\theta & \rho \cos \phi d\phi \end{bmatrix}$$



$$dx = \cos \phi \cos \theta d\rho - (4 + \rho \cos \phi) \sin \theta d\theta - \rho \sin \phi \cos \theta d\phi$$

$$dy = \cos \phi \sin \theta d\rho + (4 + \rho \cos \phi) \cos \theta d\theta - \rho \sin \phi \sin \theta d\phi$$

$$dz = \sin \phi d\rho + 0 d\theta + \rho \cos \phi d\phi$$

$$\omega = x dy dz + y dz dx + z dx dy$$

$$d\omega = ((1) + (1) + (1)) dx dy dz = 3 dx dy dz$$

$$\begin{aligned} dx dy &= \cos \phi \cos \theta d\rho (4 + \rho \cos \phi) \cos \theta d\theta - \cos \phi \cos \theta \rho \sin \phi \sin \theta d\phi d\theta - (4 + \rho \cos \phi) \sin \theta \cos \phi d\theta d\rho \\ &\quad + \rho \sin \theta \sin^2 \phi (4 + \rho \cos \phi) d\theta d\rho - \rho \sin \theta \cos \theta \cos \phi \sin \theta d\phi d\rho - (4 + \rho \cos \phi) \cos^2 \theta \rho \sin \phi d\theta d\rho \\ &= \cos \phi \cos^3 \theta (4 + \rho \cos \phi) d\rho d\theta + (4 + \rho \cos \phi) \sin^2 \theta \cos \phi d\rho d\theta - \rho \cos \theta \cos \theta \sin \phi \sin \theta d\rho d\phi \\ &\quad + \rho \sin \theta \cos \theta \cos \phi \sin \theta d\rho d\phi + \rho \sin \theta \sin^2 \phi (4 + \rho \cos \phi) d\theta d\rho + (4 + \rho \cos \phi) \cos^2 \theta \rho \sin \phi d\theta d\rho \end{aligned}$$

$$dx dy = \cos \phi (4 + \rho \cos \phi) d\rho d\theta + \rho \sin \phi (4 + \rho \cos \phi) d\theta d\phi$$

$$dx dy dz = \sin \phi (\rho \sin \phi) (4 + \rho \cos \phi) d\rho d\theta d\phi + \rho \cos \phi \cos \phi (4 + \rho \cos \phi) d\theta d\rho d\phi$$

$$dx dy dz = \sin^2 \phi \rho (4 + \rho \cos \phi) d\rho d\theta d\phi + \cos^2 \phi \rho (4 + \rho \cos \phi) d\rho d\theta d\phi$$

$$dx dy dz = \rho (4 + \rho \cos \phi) d\rho d\theta d\phi$$

$$\begin{aligned} \iiint 3 dx dy dz &= \int_0^{2\pi} \int_0^{2\pi} \int_0^1 \rho (12 + 3\rho \cos \phi) d\rho d\theta d\phi \\ &= \int_0^{2\pi} \int_0^{2\pi} (12 + 3\rho \cos \phi) d\theta d\phi \\ &= \int_0^{2\pi} \pi (12 + 3\rho \cos \phi) d\phi \\ &= 12\pi \phi + 3\pi \sin(\phi) \Big|_0^{2\pi} = \boxed{24\pi^2} \end{aligned}$$