

# Analyt II Notes

- Homework-Ch15
  - Due on Monday
- We will have Quiz 1 on Monday at 8:30am sharp!
  - Make sure your lockdown browser works
  - use “lockdown browser test” on WebAssign
  - No make-up quiz
  - Covers Ch. 15’s content

# Chapter 16: Waves - I

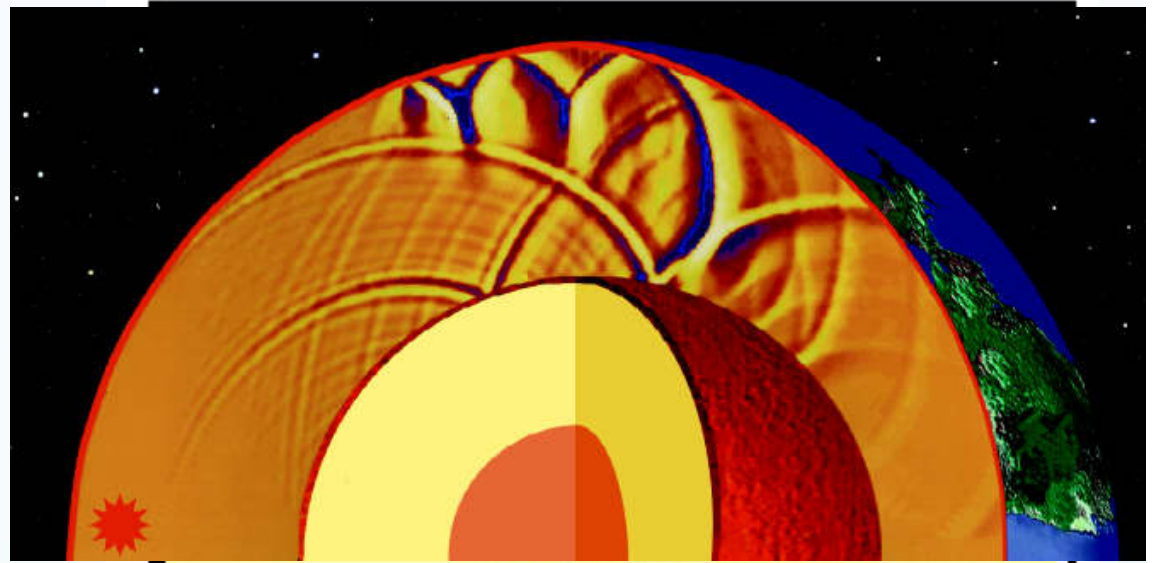
Waves are a primary subject in Physics

- Music and sounds
- Light
- Ripples on water

Types of waves :

## 1. Mechanical waves

- Involves disturbance of material
  - Water waves
  - Sound waves
  - Seismic waves
- Need a medium to propagate

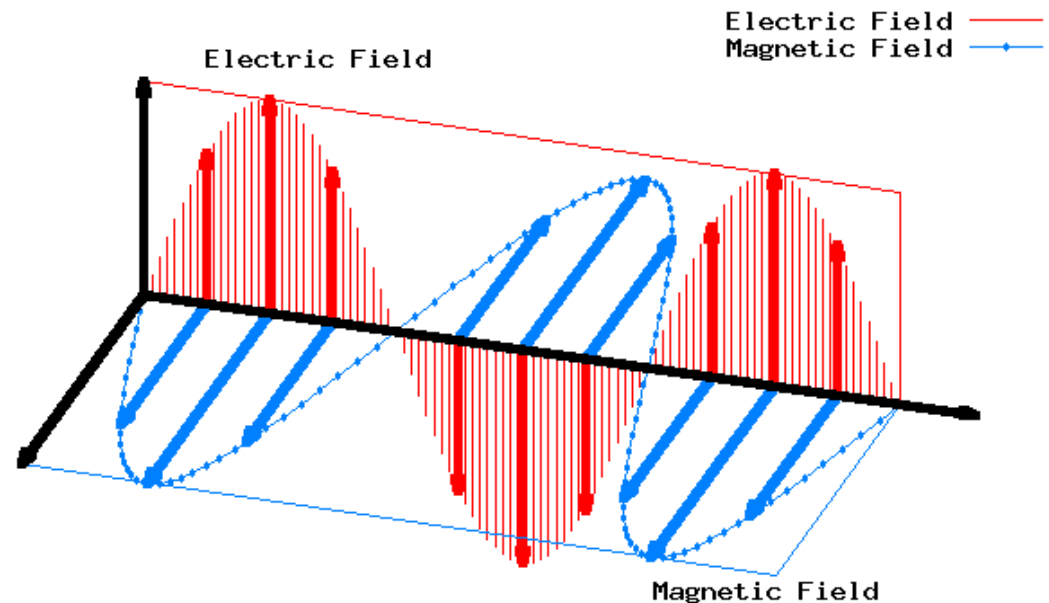


# Chapter 16: Waves - I

## Types of waves:

### 2. Electromagnetic (EM) waves

- Light (UV, radio, visible, x-rays, etc)
- Made of electric+magnetic components
- All EM waves travel at same speed ( $c \cong 3 \times 10^8$  m/s)
- No medium needed to propagate

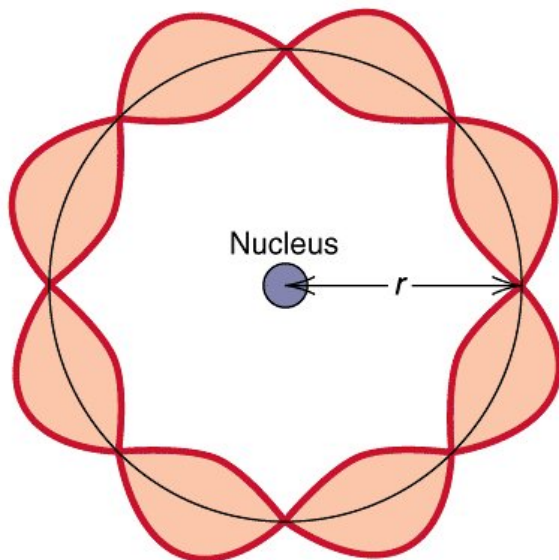


# Chapter 16: Waves - I

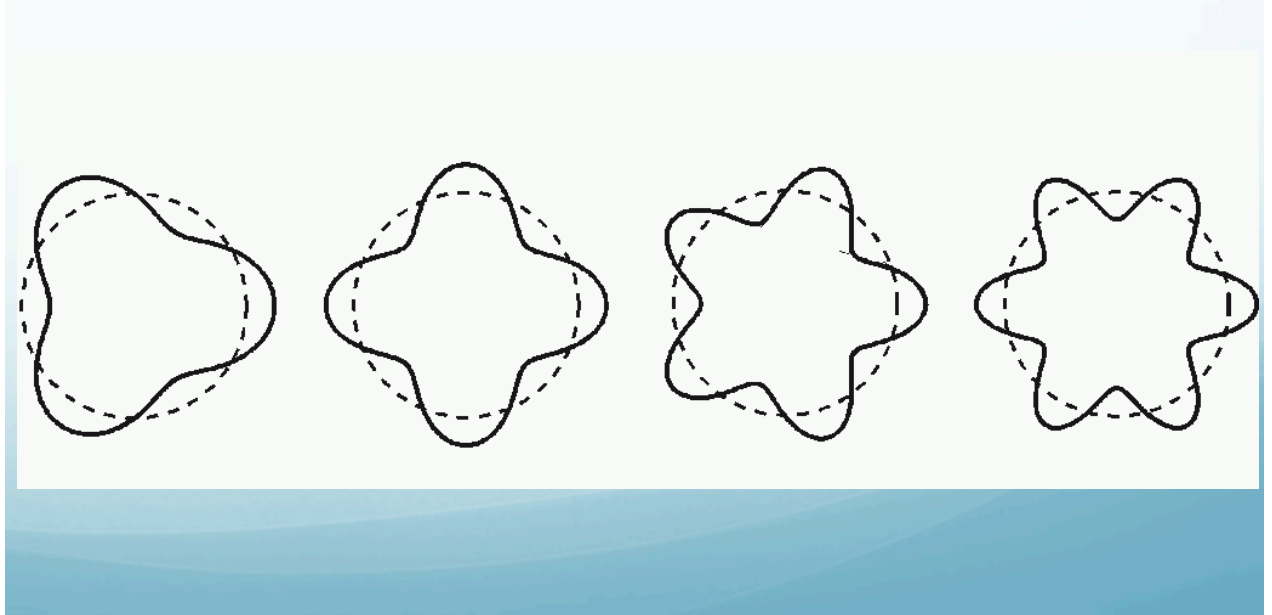
## Types of waves:

### 3. Matter waves

- Associated with fundamental particles (protons, electrons)
- Reflects wave-particle duality
- It's a concept of quantum mechanics
- Also called “de Broglie waves”



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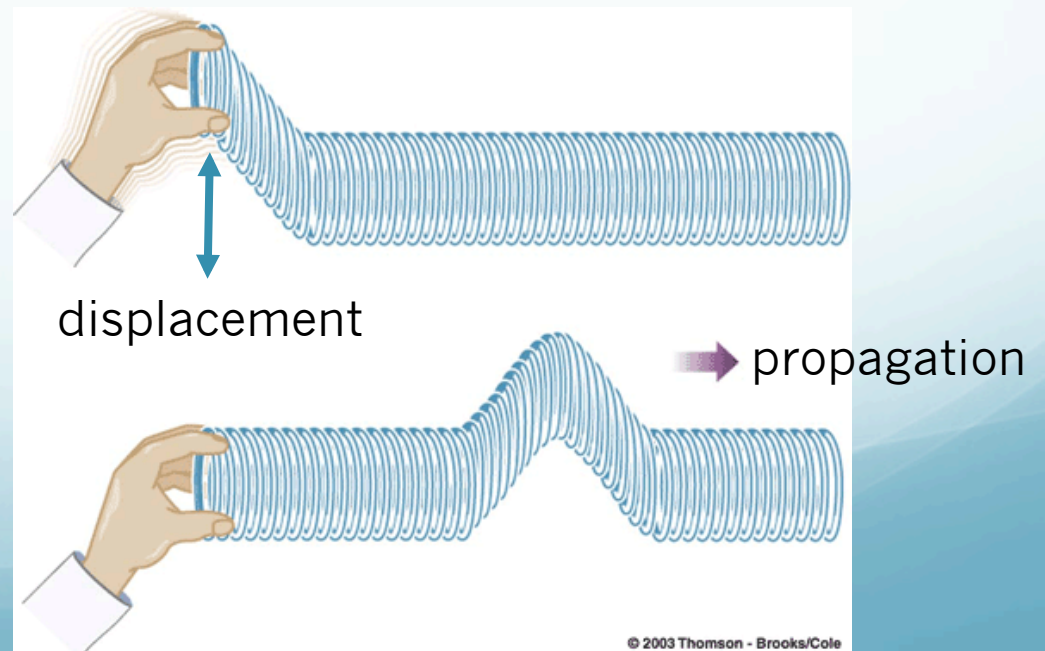


# §16-1: Transverse Waves

- ❖ A **transverse wave** is
  - disturbance for which the displacement is **perpendicular** to the propagation direction
  - The displacement forces the next section to move
  - Generates chain reaction of motion when the displacement changes with time (wave velocity)

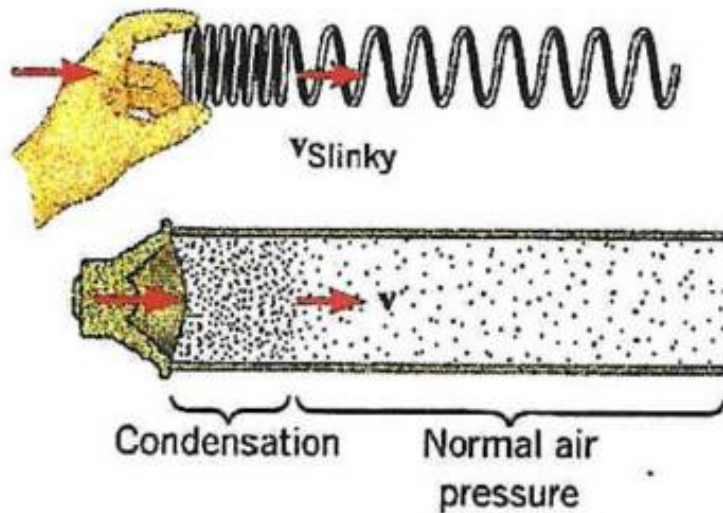
## Video examples:

- [2 pulses \(animation\)](#)
- [1 pulse \(real life\)](#)

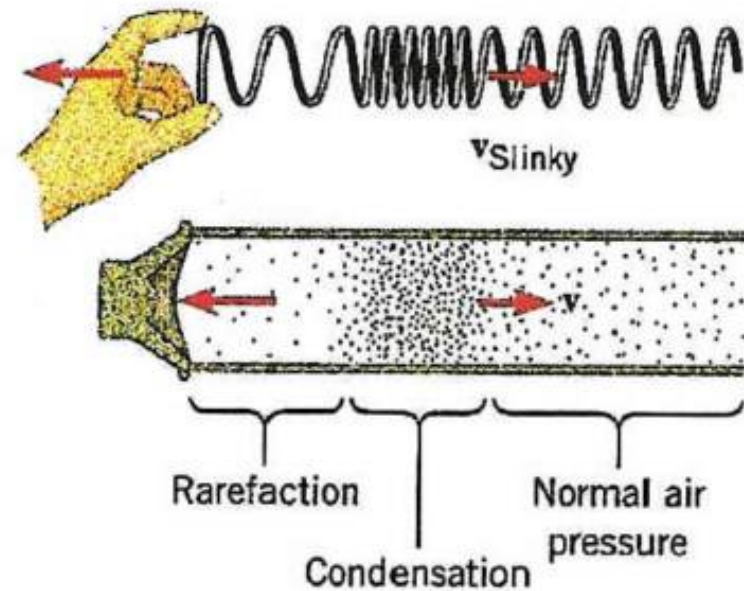


# §16-1: Longitudinal Waves

- ❖ A **longitudinal** wave is
  - disturbance for which the displacement is **parallel** to the propagation direction
  - The displacement forces the material to compress and decompress

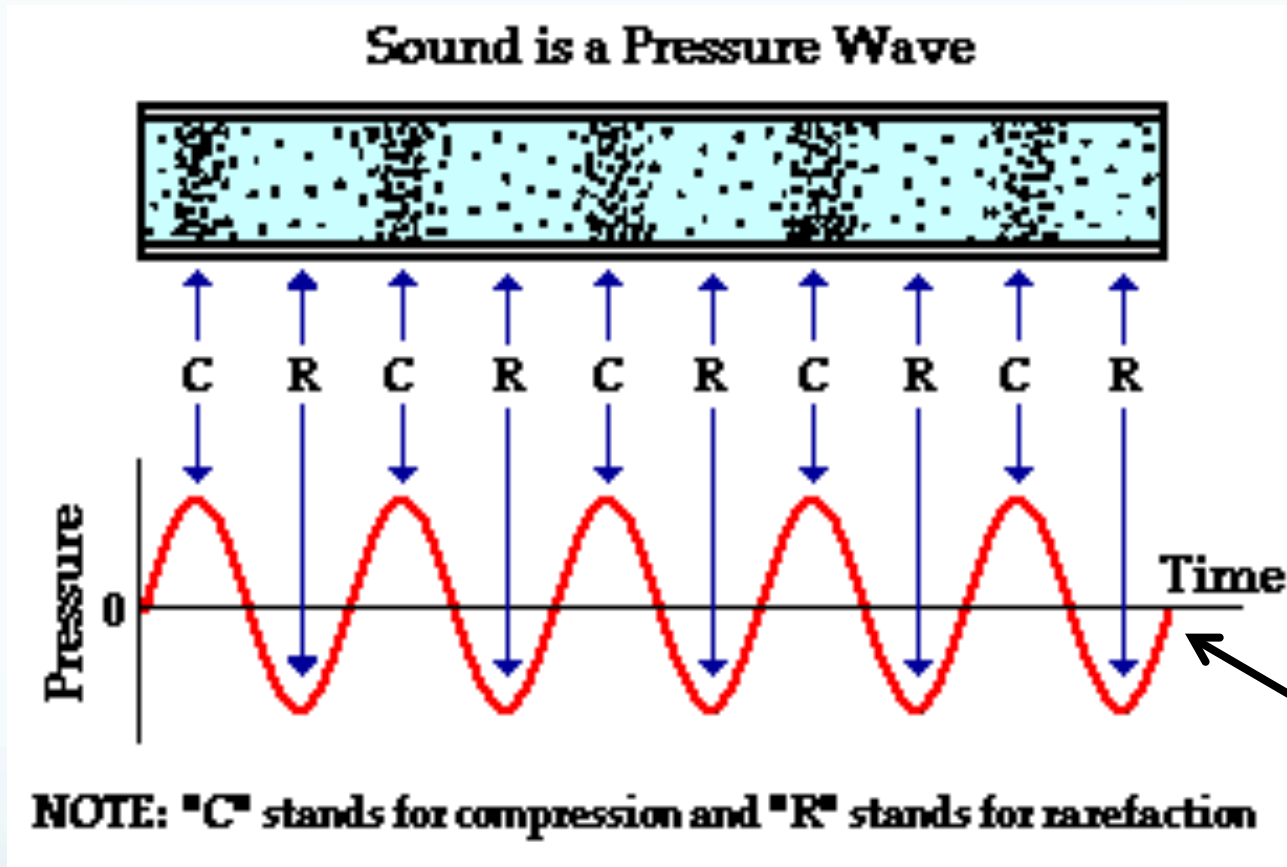


(a)



(b)

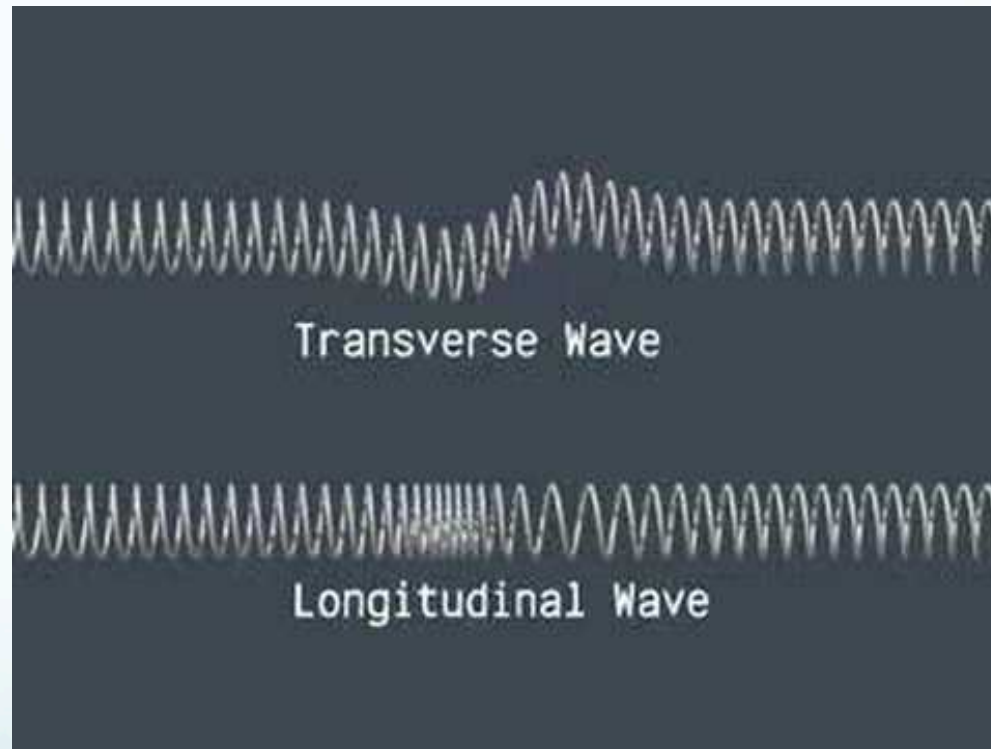
# Sound Wave is Longitudinal



Plotting pressure of air vs time, we can see the wave (that why it is also described as a compression wave)

# Transversal VS Longitudinal

- Difference is the direction of displacement with respect to the direction of propagation of wave



- Both are **“travelling” waves**, since they move from A to B
- Combination of multiple waves can lead to “standing” waves



# Wave Function

How to fully quantify a wave?

→ Need a function with a wave shape

$$y = f(x,t)$$

Where

y is the resulting displacement

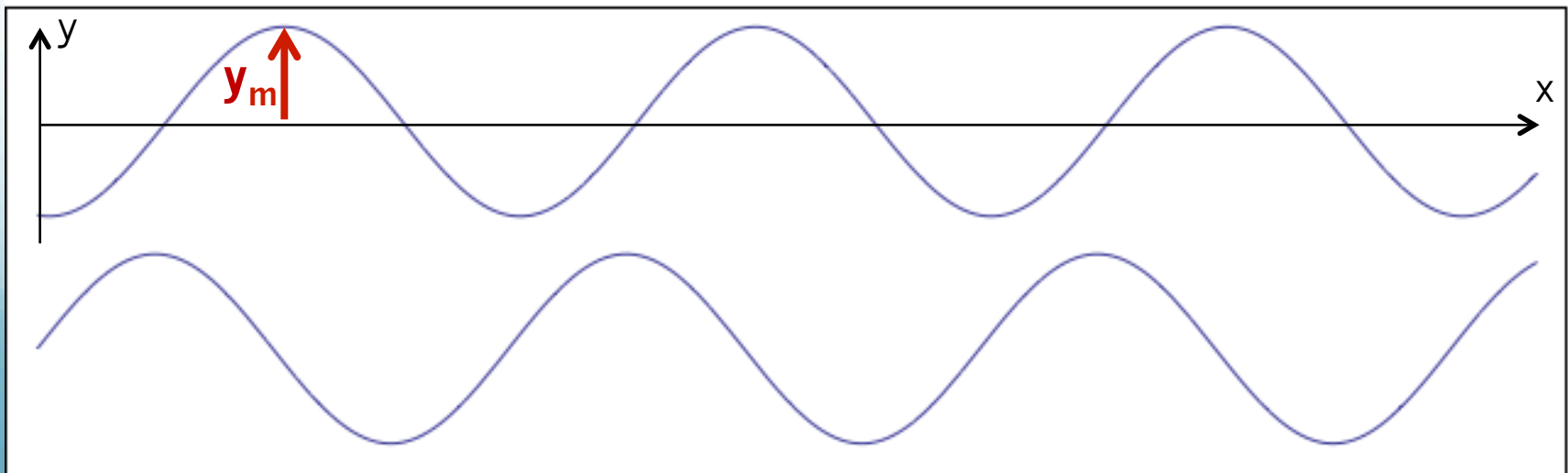
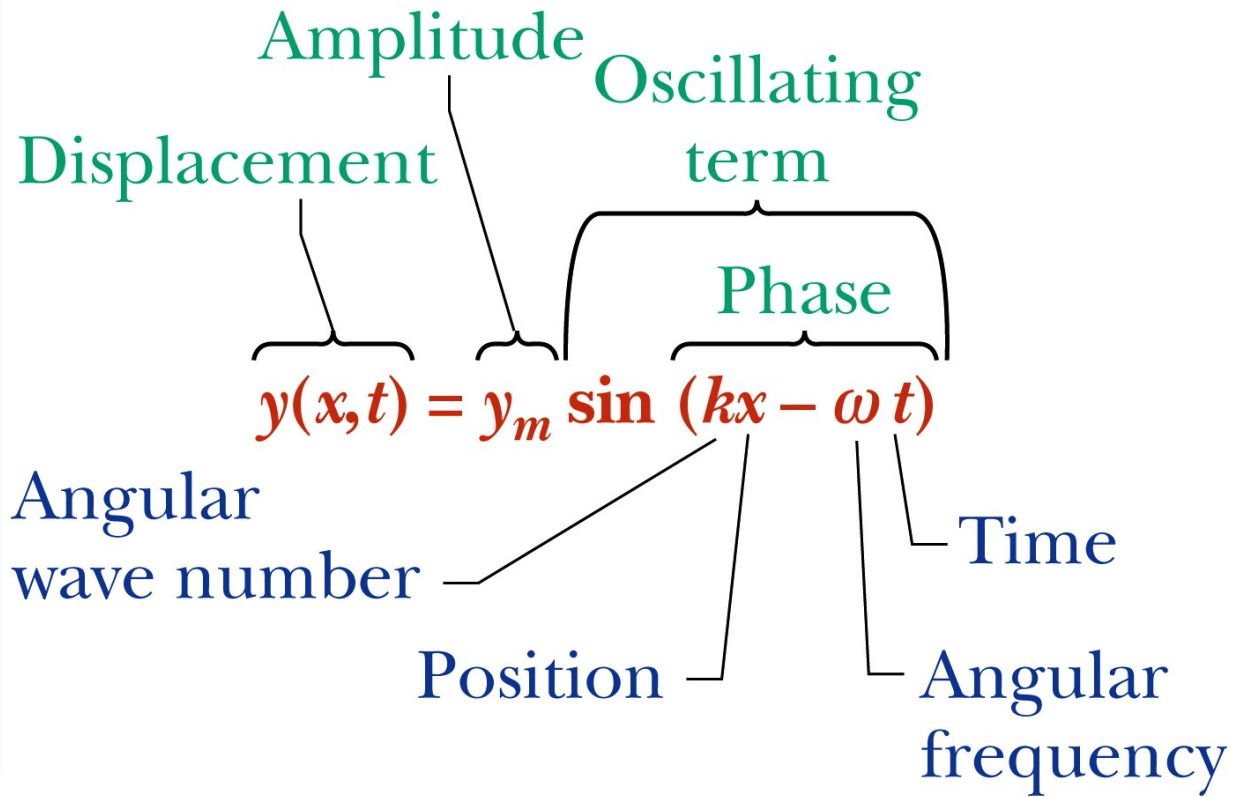
x is along the propagation direction

t is time

f(x,t) is a function that changes in time and space.

Generally, the function has a sinusoidal shape:

$$y(x,t) = y_{\max} \sin(kx - \omega t)$$



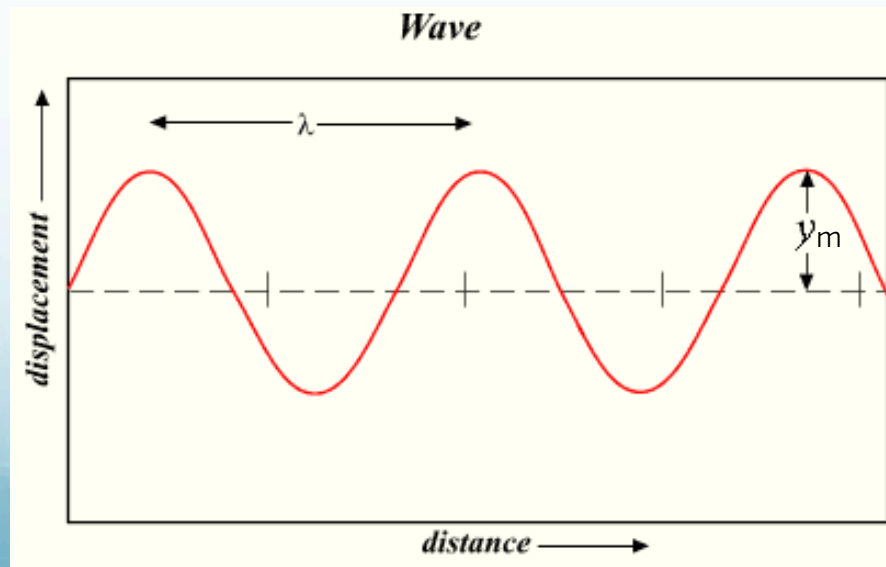
# §16-1: Wavelength and Wave Number

## Phase:

- It's the argument of sine function,  $kx - \omega t$
- Most of the wave information is in the phase

## Wavelength $\lambda$ and Angular Wave Number $k$ :

- $\lambda$  is the distance between repetitions of the shape of the wave (parallel to propagation direction)



## §16-1: Wavelength and Wave Number

$\lambda$  and  $k$  are linked together.

At a given time, say  $t=0$ , the wave function is

$$y(x, 0) = y_m \sin kx$$

At both ends of the wave, the value of  $y(x,0)$  is the same, so

$$\begin{aligned} y_m \sin kx_1 &= y_m \sin k(x_1 + \lambda) \\ &= y_m \sin(kx_1 + k\lambda) \end{aligned}$$

Because a sine function repeats itself every  $2\pi$  rad, that implies  $k\lambda = 2\pi$  (based on eq above). So...

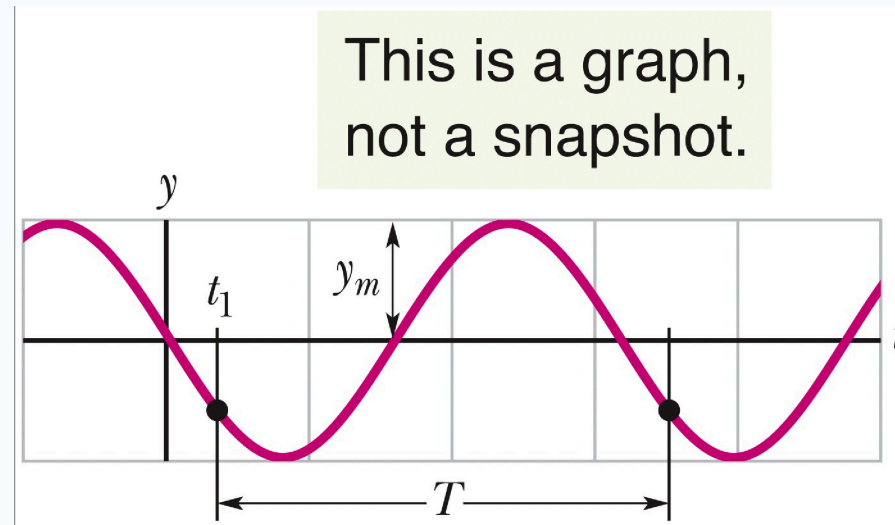
$$k = \frac{2\pi}{\lambda}$$

**angular wave number**

(Not the spring constant!!!)

## §16-1: Angular Frequency and Period

Frequency  $\omega$  and period  $T$  are also linked.



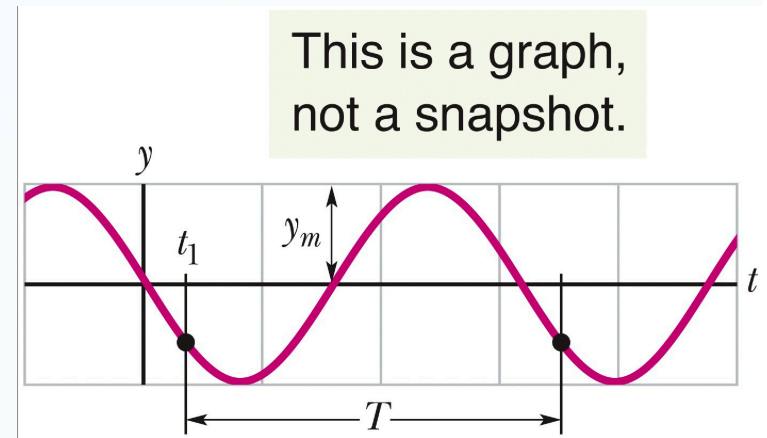
At a given position, say  $x=0$ , the string element is moving up and down with time:

$$\begin{aligned} y(0, t) &= y_m \sin(-\omega t) \\ &= -y_m \sin \omega t \quad (x = 0) \end{aligned}$$

# §16-1: Angular Frequency and Period

The time it takes for the wave to move thru a full oscillation, i.e. its period  $T$ , is the “time” between two identical  $y$  values.

Like we did for  $\lambda$  and  $k$  we find that



$$\begin{aligned} -y_m \sin \omega t_1 &= -y_m \sin \omega(t_1 + T) \\ &= -y_m \sin(\omega t_1 + \omega T) \end{aligned}$$

Therefore, since  $\omega T = 2\pi$  rad, then

$$\omega = \frac{2\pi}{T} \quad \text{angular frequency}$$

## §16-1: Phase constant $\phi$

What if a wave doesn't start at  $y(0,0) = 0$ ?

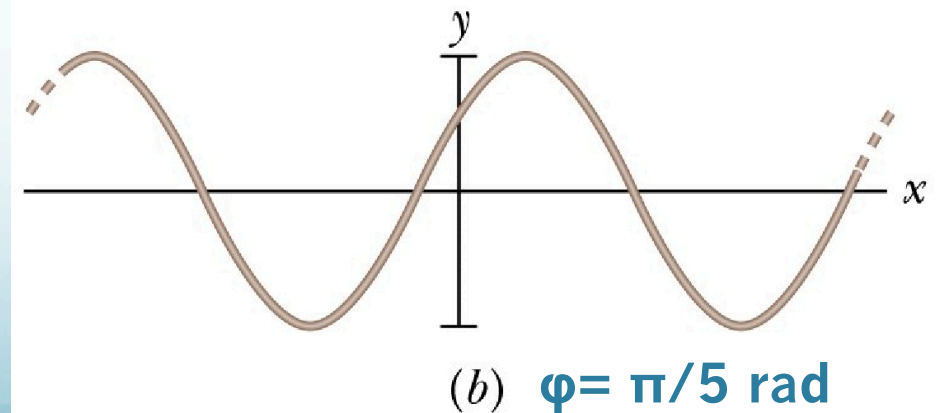
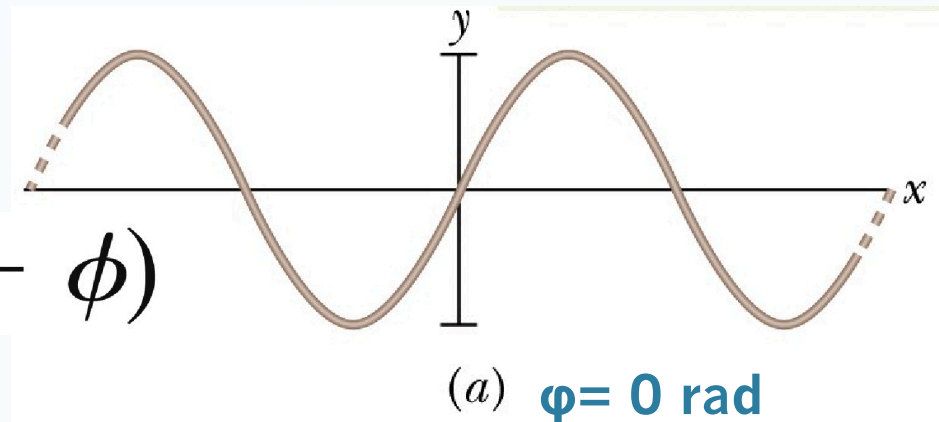
→ Means there is a shift, called **phase constant  $\phi$**

The wave function becomes:

$$y = y_m \sin(kx - \omega t + \phi)$$

The wave function has

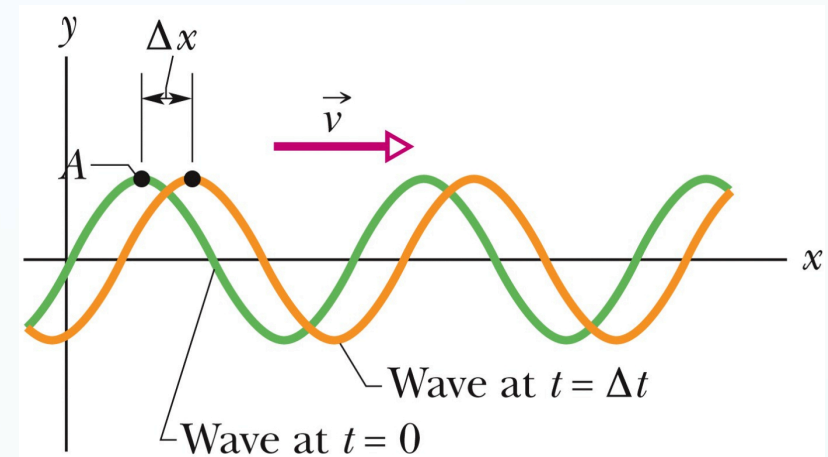
- same  $y_m$  value
- same  $\omega$  value
- same  $k$  value
- different  $\phi$  value



## §16-1: Speed of Traveling Wave

Two snapshots of a wave are taken a small time interval  $\Delta t$  apart:

- Travelling in  $+x$  direction
- Wave speed is  $\Delta x / \Delta t$   
(or also  $dx/dt$ )



Assuming the wave retains its displacement (i.e.  $\Delta x$  doesn't change with for fixed  $\Delta t$  value), that means

$$kx - \omega t = \text{a constant}$$

(in other words, only a  $\phi$  value is needed to shift wave)

We can now derive this expression to obtain  $dx/dt$ ...



## §16-1: Speed of Traveling Wave

$$kx - \omega t = \text{a constant}$$

Deriving with respect to time:

$$\frac{d}{dt}(kx - \omega t) = k \frac{dx}{dt} - \omega = 0$$

Rearranging the terms:

$$\frac{dx}{dt} = v = \frac{\omega}{k}$$

Knowing that  $k = 2\pi/\lambda$  and  $\omega = 2\pi/T$ , we obtain the expression for the **wave speed**:

$$v = \frac{\omega}{k} = \frac{\lambda}{T} = \lambda f$$

**Fundamental  
relation!!!**