

**Displacement, Speed, Velocity, and Acceleration**

$\Delta x = x_2 - x_1$  (similarly for  $\Delta y$ , etc.)

$\bar{v}_x = \frac{\Delta x}{\Delta t} = \frac{x_2 - x_1}{t_2 - t_1}$  (similarly for  $\bar{v}_y$ , etc.)

$\bar{s} = \frac{\text{total distance}}{\Delta t}$

$s = \sqrt{v_x^2 + v_y^2}$

$\bar{a} = \frac{\Delta v}{\Delta t}$

**Constant Acceleration**

$x_f = x_i + v_{ix} \Delta t + \frac{1}{2} a_x \Delta t^2$

$v_{fx} = v_{ix} + a_x \Delta t$

$v_{fx}^2 = v_{ix}^2 + 2a_x(x_f - x_i)$

$x_f = x_i + \frac{1}{2}(v_{ix} + v_{fx}) \Delta t$

**Projectile Motion**  
(assumes +y is upwards)

$a_x = 0$

$a_y = -g$

$g = +9.8 \frac{m}{s^2}$

$\tan \theta_0 = \frac{v_{0y}}{v_{0x}}$

$v_{0x} = |v_0| \cos \theta_0$

$v_{0y} = |v_0| \sin \theta_0$

$y = y_0 + (x - x_0) \left( \frac{v_{0y}}{v_{0x}} \right) - \frac{g(x - x_0)^2}{2v_{0x}^2}$

or

$y = y_0 + (x - x_0) \tan \theta_0 - \frac{g(x - x_0)^2}{2(v_0 \cos \theta_0)^2}$

$R = \frac{v_0^2}{g} \sin(2\theta_0)$

**Work, Energy, Power**

$W_F = F \cdot \Delta x \cdot \cos \theta$  (note  $\cos 180^\circ = -1$ )

$\Sigma W = KE_f - KE_i$

$KE = \frac{1}{2} m v^2$

$\bar{P} = \frac{W}{\Delta t} = F \cdot v$

$PE_{2g} = mgy_2$  if +y is upwards

$E = KE + PE_g$

$E_2 = E_1 + W_{1 \rightarrow 2, \text{all but gravity}}$  SO:

$KE_2 + PE_2 = KE_1 + PE_1 + W_{1 \rightarrow 2, \text{all but gravity}}$

**Fluids**

$\rho = \frac{m}{V}$

$\rho_{\text{water}} = 1000 \text{ kg/m}^3$

$P = \frac{F}{A}$

1 atm = 101300 Pa

$P_{\text{gauge}} = P_{\text{actual}} - P_{\text{atm}}$

$P_{\text{outlet}} = P_{\text{atm}}$

$P_{\text{bottom}} = P_{\text{top}} + \rho g(h_{\text{top}} - h_{\text{bottom}})$

$F_B = W_{\text{displaced fluid}} = \rho_{\text{fluid}} g V_{\text{sub}}$  (upwards)

$\dot{m} = \rho v A$ , and  $Q = vA$  and  $Q = \frac{V}{t}$

$\dot{m}_{\text{gain}} = \dot{m}_{\text{in}} - \dot{m}_{\text{out}}$

$P_1 + \rho g h_1 + \frac{1}{2} \rho v_1^2 = P_2 + \rho g h_2 + \frac{1}{2} \rho v_2^2$

**Springs & SHM**

$F = k \Delta L$

$PE_{\text{elastic}} = \frac{1}{2} k \Delta L^2$

$W_{\text{spring}} = -\frac{1}{2} k(x_f^2 - x_i^2)$

$\omega_{\text{natural}} = \sqrt{\frac{k}{m}}$

$x = x_{\text{max}} \cos(\omega t)$

$v_{\text{max}} = \omega x_{\text{max}}$

$a_{\text{max}} = \omega^2 x_{\text{max}}$

Pendulum :  $T = 2\pi \sqrt{\frac{L}{g}}$

$\sigma = \frac{F}{A}$

$k = \frac{YA}{L}$  for solid materials

**Forces**

Name an object or group of objects !!!!

$\Sigma F_x = ma_x$ ,  $\Sigma F_y = ma_y$

$W = mg$  (down)

$f_{s, \text{max}} = \mu_s N$

$f_k = \mu_k N$

**Vectors**

$\vec{A} = A_x \hat{x} + A_y \hat{y} + A_z \hat{z}$

$A = |\vec{A}| = \sqrt{A_x^2 + A_y^2 + A_z^2}$

$\theta = \arctan\left(\frac{A_y}{A_x}\right)$

$A_x = A \cos \theta$

$A_y = A \sin \theta$

**Gravity**

$F = G \frac{m_1 m_2}{r^2}$

$G = 6.67 \times 10^{-11} \frac{\text{Nm}^2}{\text{kg}^2}$

$T = 2\pi \sqrt{\frac{R^3}{GM}}$

**Center of Mass**

$x_{CM} = \frac{1}{m_{\text{tot}}} \Sigma m_i x_i$

**Momentum & Impulse**

$\vec{p} = m\vec{v}$

$\Sigma \vec{F} \cdot \Delta t = \Delta \vec{p}$

$\Sigma \vec{F}_x \cdot \Delta t = m(v_{fx} - v_{ix})$

$\vec{p}_f = \vec{p}_i$  if  $\Sigma \vec{F} = 0$

$\vec{J} = \Sigma \vec{F} \cdot \Delta t$

**1D Elastic Collisions**

$v_{1f} = \frac{m_1 - m_2}{m_1 + m_2} v_{1i} + \frac{2m_2}{m_1 + m_2} v_{2i}$

$v_{2f} = \frac{2m_1}{m_1 + m_2} v_{1i} + \frac{m_2 - m_1}{m_1 + m_2} v_{2i}$

**Circular Motion & Rotation**

$|a_c| = \frac{v^2}{r} = r\omega^2$  towards the center of the circle

$|a_t| = r\alpha$

$T = \frac{2\pi r}{v} = \frac{2\pi}{\omega} = \frac{1}{f}$  (constant speed)

$s = r\Delta\theta$  (distance traveled,  $\Delta\theta$  in radians)

$T = 2\pi \sqrt{\frac{R^3}{GM}}$  (orbits)

$\Delta\theta = \theta_f - \theta_i$

$\omega_{\text{average}} = \frac{\Delta\theta}{\Delta t}$

$\alpha_{\text{average}} = \frac{\Delta\omega}{\Delta t}$

$v = R\omega$  (on a rotating object)

$r_A \omega_A = r_B \omega_B$  (gears)

**Rolling**

$N = \frac{L}{2\pi R}$

$v_{CM} = R\omega$

$a_{CM} = R\alpha$

**Torque**

$\Sigma \tau = I\alpha$

$|\tau| = |R_{\perp} F|$

$I_{\text{particle}} = mr^2$

$I_{\text{parallelaxis}} = I_{CM} + m\ell^2$

$KE_{\text{rotation}} = \frac{1}{2} I \omega^2$

$W = \tau \Delta\theta$

$L = I\omega$   $L_{\text{particle}} = m r_{\perp} v$

$\Sigma \tau \Delta t = \Delta L$

**Constant Angular Acceleration**

$\theta = \theta_0 + \omega_0 \Delta t + \frac{1}{2} \alpha \Delta t^2$

$\omega = \omega_0 + \alpha \Delta t$

$\omega^2 = \omega_0^2 + 2\alpha(\theta - \theta_0)$

$\theta - \theta_0 = \frac{1}{2}(\omega + \omega_0) \Delta t$

**Heat**

$T > 0K$

$E_{\text{thermal}} = mcT$

$\Delta L = L_{\text{orig}} \alpha \Delta T$

$\Delta V = V_{\text{orig}} \beta \Delta T$

$\beta = 3\alpha$

$\dot{Q}_{\text{radiation}} = \frac{Q}{\Delta t} = e\sigma AT^4$

$\sigma = 5.67 \times 10^{-8} \frac{\text{J}}{\text{sm}^2 \text{K}^4}$

$\dot{Q}_{\text{conduction}} = \frac{Q}{\Delta t} = \frac{kA \Delta T}{L}$